

## **L.EEC025 - FUNDAMENTALS OF SIGNAL PROCESSING**

*Academic year 2024-2025, week 1*  
*PL preliminary exercises*

**Topics:** Introduction to Matlab, revisiting the discrete-time convolution, FIR/IIR discrete-time systems

### **Problem 1**

Create an .m file of Matlab commands implementing the following operations:

- asks the user to enter an integer number  $N$  ( $N > 30$ ) using the keyboard,
- creates a line vector,  $n$ , including the integers  $0, 1, \dots, N-1$ ,
- creates a line vector  $h = \alpha^n$  with  $\alpha = 0.95 \exp(j\pi/3)$ ,
- represents graphically the absolute value of the elements of vector  $h$ , using vector  $n$  to index the abscissae axis;
- also adds the following commands:

```
>> xlabel('n \rightarrow');  
>> ylabel('Magnitude \rightarrow');  
>> legend('Envelope')  
>> title('Complex Exponential');
```

(OBS: always use command `pause`; after a plot or `stem` command)
- starts a new graphical window using `figure(2)`; this figure will then be split in order to represent three plots vertically (i.e., it will be configured as a  $3 \times 1$  matrix),
- uses command `stem` to represent in the upper part of figure 2, the real part of vector  $h$ , and using vector  $n$  to index the abscissae axis;
- creates a line vector  $x$ , comprising  $N$  elements and whose non-zero values are given by the discrete-time sequence  $u[n-20] - u[n-30]$ ,
- uses command `stem` to represent in the middle part of figure 2, vector  $x$ , and using vector  $n$  to index the abscissae axis;
- uses command `conv` to create in vector  $y$  the result of the discrete convolution between the real part of vector  $h$  and vector  $x$ ;
- displays the message "Convolution completed!",
- shows the result of commands `size(y)` and `length(y)` (what is the difference?),
- uses command `stem` to represent in the lower part of figure 2, the first  $N$  elements of vector  $y$  using symbol 'pentagram', and using vector  $n$  to index the abscissae axis;
- adds suitable labels to the abscissae and ordinates axis of figure 2.

Find yourself the answers to these questions:

- i) Commands `sum(h.*conj(h))` and `h*h'` deliver the same result, why?
- ii) What is the difference between `h*h'` and `h*h.'`? And if we had instead `h.*h`?
- iii) Where we used command `conv`, could we have used command `filter`?
- iv) What is the difference between commands `who` and `whos`?

## Exercise 2

A discrete-time system is described by the difference equation  $y[n] = \frac{1}{4}(x[n] + x[n-1] + x[n-2])$ .

- Obtain its impulse response,  $h[n]$ .
- Obtain the output of the system to the input  $x[n] = 0.5\delta[n] + \delta[n-1] + 0.5\delta[n-2]$ .
- Confirm the previous result using Matlab.

## Exercise 3

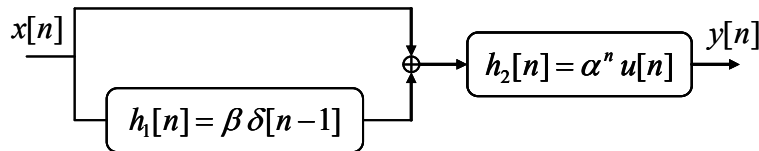
The impulse response of a discrete-time system is given by  $h[n] = 2^{-n}u[n]$ . Obtain the output of the system when the input is  $x[n] = u[n] - u[n-10]$ . Confirm the result using Matlab.

## Exercise 4

Obtain the impulse response of the system that is described by the difference equation  $y[n] = 0.3x[n] + 0.7y[n-1]$  and assuming that it starts from rest. Confirm the result using Matlab.

## Exercise 5

In the illustrated discrete-time system (consisting of several subsystems)  $\alpha$  and  $\beta$  are real-valued constants whose absolute value is less than the unity.



- Obtain the impulse response of the complete system,  $h[n]$ .
- Obtain the frequency response of the complete system,  $H(e^{j\omega})$ .
- Obtain a difference equation (relating  $y[n]$  and  $x[n]$ ) describing the complete system.